# Quadrilaterals as Geometric Loci 

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#### Abstract

We give necessary and sufficient conditions, both algebraic and geometric, for a quadrilateral to be the level set of the sum of the distances to $m \geq 2$ different lines.


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## 1. Introduction

In [6] the authors set out to design a single Cartesian equation in variables $(x, y)$ whose set of solutions is a quadrilateral in the Euclidean plane $\mathbb{R}^{2}$ whose vertices are given by their coordinates. Apart from the four basic arithmetic operations, the equation contains only the absolute value as a further operation. The method presented in the said article works well for most convex quadrilaterals (though not all) but is cumbersome for non-convex or crossed quadrilaterals. We briefly describe the approach in [6]: Let $\left(x_{0}, y_{0}\right),\left(x_{1}, y_{1}\right),\left(x_{2}, y_{2}\right)$, $\left(x_{3}, y_{3}\right)$ be the Cartesian coordinates of the vertices of a quadrilateral where its perimeter is traversed in the corresponding order of the vertices. Solve the linear system

$$
\underbrace{\left(\begin{array}{cccccccr}
x_{0} & y_{0} & 1 & 0 & 0 & 0 & 0 & 0  \tag{1}\\
x_{1} & y_{1} & 1 & 0 & 0 & 0 & -x_{1} & -y_{1} \\
x_{2} & y_{2} & 1 & 0 & 0 & 0 & 0 & 0 \\
x_{3} & y_{3} & 1 & 0 & 0 & 0 & x_{3} & y_{3} \\
0 & 0 & 0 & x_{0} & y_{0} & 1 & -x_{0} & -y_{0} \\
0 & 0 & 0 & x_{1} & y_{1} & 1 & 0 & 0 \\
0 & 0 & 0 & x_{2} & y_{2} & 1 & x_{2} & y_{2} \\
0 & 0 & 0 & x_{3} & y_{3} & 1 & 0 & 0
\end{array}\right)}_{=: M}\left(\begin{array}{l}
A \\
B \\
C \\
D \\
E \\
F \\
G \\
H
\end{array}\right)=\left(\begin{array}{r}
0 \\
1 \\
0 \\
-1 \\
1 \\
0 \\
-1 \\
0
\end{array}\right) .
$$

Then the equation which describes the boundary of the quadrilateral is given by

$$
\begin{equation*}
\left|\frac{A x+B y+C}{G x+H y+I}\right|+\left|\frac{D x+E y+F}{G x+H y+I}\right|=1 . \tag{2}
\end{equation*}
$$

Observe, however, that for given $\left(x_{0}, y_{0}\right),\left(x_{1}, y_{1}\right),\left(x_{2}, y_{2}\right)$ the equation $\operatorname{det} M=0$ is quadratic in the variables $\left(x_{3}, y_{3}\right)$ and describes a conic through the points $\left(x_{0}, y_{0}\right),\left(x_{1}, y_{1}\right),\left(x_{2}, y_{2}\right)$. For example, for $\left(x_{0}, y_{0}\right)=(1,1)$, $\left(x_{1}, y_{1}\right)=(-1,2),\left(x_{2}, y_{2}\right)=(-1,1)$, we obtain the conic $3+x^{2}-6 y+2 y^{2}=0$ (see Figure 1). For all points $\left(x_{3}, y_{3}\right)$ on this conic (different from the three given points), the equation (1) has no solution.

[^0]

Figure 1. For all convex quadrilaterals with fixed vertices $\left(x_{0}, y_{0}\right),\left(x_{1}, y_{1}\right),\left(x_{2}, y_{2}\right)$ and fourth point $\left(x_{3}, y_{3}\right)$ on the red ellipse the equation (1) has no solution.

The problem with a non-convex or a crossed quadrilateral is, that equation (2) draws a convex solution in the projective plane that passes over the ideal line (see Figure 2).


Figure 2. A non-convex quadrilateral.

Nevertheless, it is also possible to write the non-convex boundary of the quadrilateral in Figure 2 as the level set of a single Cartesian equation: The vertices are $\left(x_{0}, y_{0}\right)=(0,0),\left(x_{1}, y_{1}\right)=(1,1),\left(x_{2}, y_{2}\right)=(-2,0)$, $\left(x_{3}, y_{3}\right)=(1,-1)$. Then the quadrilateral is the level set

$$
\begin{equation*}
\left\{x \in \mathbb{R}^{2}: \max \left(\max \left(\left\langle n_{1}, x\right\rangle-d_{1},\left\langle n_{2}, x\right\rangle-d_{2}\right), \min \left(\left\langle n_{3}, x\right\rangle-d_{3},\left\langle n_{4}, x\right\rangle-d_{4}\right)\right)=1\right\} \tag{3}
\end{equation*}
$$

Here

$$
n_{1}=\sqrt{\frac{1}{10}}(-1,-3)^{t}, n_{2}=\sqrt{\frac{1}{10}}(-1,3)^{t}, n_{3}=\sqrt{\frac{1}{2}}(1,-1)^{t}, n_{4}=\sqrt{\frac{1}{2}}(1,1)^{t}
$$

are the outer unit normal vectors of the sides of the quadrilateral, $\langle\cdot, \cdot\rangle$ is the Euclidean inner product, and $d_{1}=d_{2}=\sqrt{\frac{2}{5}}-1, d_{3}=d_{4}=-1$. Notice also that the minimum and the maximum function in (3) can be expressed with the absolute value:

$$
\min (a, b)=\frac{1}{2}(a+b-|a-b|), \quad \max (a, b)=\frac{1}{2}(a+b+|a-b|) .
$$

We refrain from giving a general formula for this problem here, but focus now on the actual goal of this article: Let $f: \mathbb{R}^{2} \rightarrow \mathbb{R}, x \mapsto f(x)$, denote the (weighted) sum of the distances of a point $x$ to a set of given straight lines $\ell_{1}, \ldots, \ell_{m}$. We then ask, which quadrilaterals can be written as the level set of such a function $f$.

This question is also motivated by Descartes' solution of Pappus' problem as described in Chapter 23 of [2]: Given $m$ straight lines $\ell_{i}$ in the plane, $n$ angles $\theta_{i}$, and a line segment $a$. For any point $x$ in the plane, the oblique distances $\delta_{i}$ to the lines $\ell_{i}$ are defined as the (positive) lengths of segments that are drawn from $x$ toward $\ell_{i}$
making angle $\theta_{i}$ with $\ell_{i}$. Find the locus of points $x$ for which the following ratios are constant:

$$
\begin{aligned}
& \text { for } m=3 \text { lines } \quad \delta_{1}^{2}: \delta_{2} \delta_{3} \\
& \text { for } m=2 k \geq 4 \text { lines } \quad \delta_{1} \ldots \delta_{k}: \delta_{k+1} \ldots \delta_{2 k} \\
& \text { for } m=2 k+1 \geq 5 \text { lines } \quad \delta_{1} \ldots \delta_{k+1}: a \delta_{k+2} \ldots \delta_{2 k+1}
\end{aligned}
$$

Instead of oblique distances, we can equivalently work with weighted normal distances (see Figure 3).


Figure 3. Oblique distances interpreted as weighted normal distances: $\delta_{i}=d_{i} \csc \left(\theta_{i}\right)$

The classical Greek geometry has considered the following loci:

- the sum of the distances to two given points is a constant (this gives an ellipse),
- the ratio of the distances to two points is a constant (this gives a circle of Apollonius),
- the ratio of (products of) distances to straight lines is a constant (this is Pappus' problem).

But the sum of the distances to straight lines appears then only in Viviani's theorem from 1649, and in its generalizations (see, e.g., [1]). However, there the question is not about the locus. In this sense we close a gap here by considering the locus of the set of points for each of which the sum of the distances to given straight lines is a constant.

## 2. Weighted distances to three lines

Before we start we fix some notation which we will use throughout this text. The vertices of the quadrilateral will be denoted by $A, B, C, D$. We will consider the corresponding complete quadrangle and denote by $E$ the intersection of $A B$ and $C D$, and by $F$ the intersection of $A D$ and $B C$ (see Figure (5). $\ell_{1}$ is the diagonal $A C$, $\ell_{2}$ the diagonal $B D$, and $\ell_{3}^{\prime}$ the diagonal $E F$. The intersections of the diagonals are $O=\ell_{1} \cap \ell_{2}, P=\ell_{1} \cap \ell_{3}^{\prime}$, and $Q=\ell_{2} \cap \ell_{3}^{\prime}$. When we work with vectors, $O$ will be the origin. Moreover, we use the notation $a=|O A|$, $b=|O B|, c=|O C|, d=|O D|, p=|O P|, q=|O Q|$ for the lengths of the respective segments.
In this section we treat the question which quadrilaterals can be described as level sets of the weighted sum of the distances to three lines. Suppose we are given a convex quadrilateral $A B C D$ in the Euclidean plane. By choosing unit normal vectors $n_{1}, n_{2}$ to $\ell_{1}, \ell_{2}$, and $M=\left(\begin{array}{rr}0 & -1 \\ 1 & 0\end{array}\right)$ we may write $A=-a M n_{1}, B=b M n_{2}$, $C=c M n_{1}, D=-d M n_{2}$.
A further line $\ell_{3}$ which does not meet the quadrilateral and with unit normal vector $n_{3}$ will be determined later. We assume that the orientation of $n_{3}$ is such that the quadrilateral lies in the half plane with boundary $\ell_{3}$ in which $n_{3}$ points. The line $\ell_{i}$ is given by the equation

$$
\left\langle n_{i}, x\right\rangle-d_{i}=0, \quad\left\|n_{i}\right\|=1,
$$

where $x=\left(x_{1}, x_{2}\right) \in \mathbb{R}^{2}$ runs along $\ell_{i}$. The distance of a point $x \in \mathbb{R}^{2}$ from $\ell_{i}$ is given by the function

$$
f_{i}(x)=\left|\left\langle n_{i}, x\right\rangle-d_{i}\right| .
$$



Figure 4. The quadrilateral $A B C D$.

The weighted sum of the distances of $x$ to $\ell_{1}, \ell_{2}$ and $\ell_{3}$ is

$$
f(x)=\sum_{i=1}^{3} k_{i} f_{i}(x)
$$

for weights $k_{i} \geq 0$. Then the gradient of $f$ along the boundary of the quadrilateral is given as follows:

$$
\begin{array}{ll}
\text { along } s_{1} & \nabla f=k_{1} n_{1}+k_{2} n_{2}+k_{3} n_{3} \\
\text { along } s_{2} & \nabla f=k_{1} n_{1}-k_{2} n_{2}+k_{3} n_{3} \\
\text { along } s_{3} & \nabla f=-k_{1} n_{1}-k_{2} n_{2}+k_{3} n_{3} \\
\text { along } s_{4} & \nabla f=-k_{1} n_{1}+k_{2} n_{2}+k_{3} n_{3}
\end{array}
$$

The gradient of $f$ along $s_{1}$ is perpendicular to $s_{1}$, and hence there exists $\alpha \in \mathbb{R} \backslash\{0\}$ such that

$$
-\alpha M\left(b M n_{2}+a M n_{1}\right)=k_{1} n_{1}+k_{2} n_{2}+k_{3} n_{3}
$$

or equivalently

$$
\begin{equation*}
k_{3} n_{3}=n_{1}\left(\alpha a-k_{1}\right)+n_{2}\left(\alpha b-k_{2}\right) \tag{4}
\end{equation*}
$$

Similarly, with $s_{2}, s_{3}, s_{4}$ in place of $s_{1}$, we obtain

$$
\begin{align*}
k_{3} n_{3} & =n_{1}\left(\beta c-k_{1}\right)+n_{2}\left(-\beta b+k_{2}\right)  \tag{5}\\
k_{3} n_{3} & =n_{1}\left(-\gamma c+k_{1}\right)+n_{2}\left(-\gamma d+k_{2}\right)  \tag{6}\\
k_{3} n_{3} & =n_{1}\left(-\delta a+k_{1}\right)+n_{2}\left(\delta d-k_{2}\right) \tag{7}
\end{align*}
$$

Since $n_{1}$ and $n_{2}$ are linearly independent, we infer from (4)-(7)

$$
\begin{aligned}
\alpha a-k_{1} & =\beta c-k_{1}=-\gamma c+k_{1}=-\delta a+k_{1} \\
\alpha b-k_{2} & =-\beta b+k_{2}=-\gamma d+k_{2}=\delta d-k_{2} .
\end{aligned}
$$

It follows that

$$
\alpha=2 \epsilon c d, \beta=2 \epsilon a d, \gamma=2 \epsilon a b, \delta=2 \epsilon b c
$$

for arbitrary $\epsilon>0$, and

$$
k_{1}=\epsilon a c(b+d), k_{2}=\epsilon b d(a+c), k_{3} n_{3}=n_{1} \epsilon a c(d-b)+n_{2} \epsilon b d(c-a) .
$$

It turns out that this result has a nice geometric interpretation which can be seen by choosing $\epsilon=\frac{2}{(a+c)(b+d)}$. Then the wights

$$
\begin{equation*}
k_{1}=\frac{2 a c}{a+c}, \quad k_{2}=\frac{2 b d}{b+d} \tag{8}
\end{equation*}
$$

are the harmonic means of the segments of the diagonals, and

$$
k_{3} n_{3}=n_{1} \frac{2 a c(d-b)}{(a+c)(b+d)}+n_{2} \frac{2 b d(c-a)}{(b+d)(c+a)} .
$$

We consider the following three cases:

1. Suppose $a=c$ and $b=d$. In this case the quadrilateral is a parallelogram, and we have $k_{3}=0$. Hence, in this case, the third line $\ell_{3}$ is not necessary.
2. Suppose $a=c$ and $b<d$ (the case $b>d$ is symmetric). In this case the quadrilateral is an oblique kite, and we have

$$
\begin{equation*}
k_{1}=a, \quad k_{2}=\frac{2 b d}{b+d}, \quad k_{3}=a \frac{d-b}{b+d}, \quad n_{3}=n_{1} . \tag{9}
\end{equation*}
$$

This means that the third line $\ell_{3}$ is parallel to $n_{1}$.
3. Suppose $a \neq c$ and $b \neq d$. Without loss of generality we assume $a>c, b>d . P \in \ell_{1}$ is the harmonic conjugate of $O$ with respect to $A$ and $C$, and $Q \in \ell_{2}$ is the harmonic conjugate of $O$ with respect to $B$ and $D$ (see [4], and Figure 5). Then the distances of $P$ and $Q$ respectively from $O$ are

$$
\begin{equation*}
p=\frac{2 a c}{a-c}, \quad q=\frac{2 b d}{b-d} . \tag{10}
\end{equation*}
$$



Figure 5. The complete quadrangle $A B C D$.

A simple calculation shows that

$$
\begin{equation*}
\frac{(a-c)(b-d)}{(a+c)(b+d)} M \overrightarrow{P Q}=-k_{3} n_{3} . \tag{11}
\end{equation*}
$$

Hence, $\ell_{3}$ is parallel to the outer diagonal $\ell_{3}^{\prime}$. Observe that (11) also shows that $-n_{3}$ points towards the half plane bounded by $\ell_{3}^{\prime}$ which contains the quadrilateral $A B C D$. Hence we must choose $\ell_{3} \| \ell_{3}^{\prime}$ on the other side of the quadrilateral $A B C D$. What we also learn from (11) is that

$$
\begin{equation*}
k_{3}=\frac{(a-c)(b-d)}{(a+c)(b+d)}|P Q| . \tag{12}
\end{equation*}
$$

To summarize we have the following result.

Theorem 1. 1. Every parallelogram is the level set of a weighted sum of the distances to its diagonals. The weights are given by (8).
2. Every convex oblique kite is the level set of a weighted sum of the distances to its diagonals and a third line parallel to the diagonal which is bisected by the other. The weights are given by (9).
3. Every convex quadrilateral which is neither a parallelogram nor an oblique kite is the level set of a weighted sum of the distances to its diagonals and a third line which is parallel to the outer diagonal of the complete quadrangle. The weights are given by (8) and (12).

We remark, that for a parallelogram, the points $E, F, P, Q$ lie on the ideal line (of the projective plane), for an oblique kite, $P$ or $Q$ lies on the ideal line, and for a trapezoid, $E$ or $F$ lies on the ideal line.

## 3. Distances to an arbitrary number of lines

If we restrict ourselves to the case of an unweighted sum, the question arises which quadrilaterals occur as level sets of the sum of the distances to two or more lines. We start with the general case of $m \geq 2$ lines.

### 3.1. A necessary condition

Let $\ell_{1}, \ldots, \ell_{m}$ be different straight lines in the Euclidean plane $\mathbb{R}^{2}, m \geq 2$. The line $\ell_{i}$ is again given by the equation

$$
\left\langle n_{i}, x\right\rangle-d_{i}=0, \quad\left\|n_{i}\right\|=1
$$

where $x=\left(x_{1}, x_{2}\right) \in \mathbb{R}^{2}$ runs along $\ell_{i}$, and $n$ is a unit normal vector of $\ell_{i}$. The distance of a point $x \in \mathbb{R}^{2}$ to $\ell_{i}$ is given by the function

$$
f_{i}(x)=\left|\left\langle n_{i}, x\right\rangle-d_{i}\right| .
$$

The sum of the distances of $x$ to $\ell_{1}, \ldots, \ell_{m}$ is

$$
f(x)=\sum_{i=1}^{m} f_{i}(x)
$$

As a sum of convex functions, $f$ is also convex. We assume that at least two of the lines $\ell_{i}$ are not parallel. Then it follows that $f$ is coercive and hence the level sets of $f$ are bounded. The lines $\ell_{i}$ divide the plane into convex poygonal regions. On each such region, $f$ is an affine function. Therefore, $f$ attains its minimum either in a single point (a vertex of one of the mentioned polygons), along a line segment (the side of one of the polygons), or in all points of one of the polygons. Let us assume, that $f$ has a unique minimum in a point $x_{0} \in \mathbb{R}^{2}$. By suitable choice of the coordinate system we can achieve $x_{0}=0$. Let us further assume that only two of the lines, say $\ell_{1}$ and $\ell_{2}$ pass through the origin, which we denote by $O$. Then the level sets

$$
\left\{x \in \mathbb{R}^{2}: f(x)=h\right\}
$$

are quadrilaterals for all $h \in(f(0), f(0)+\varepsilon)$ provided $\varepsilon>0$ is sufficiently small. Let $a, b, c, d$ continue to denote the positive distances of the vertices of the quadrilateral from $O$ (see Figure 6). Then, with

$$
M=\left(\begin{array}{rr}
0 & -1 \\
1 & 0
\end{array}\right)
$$

the vertices are given by $-a M n_{1}, b M n_{2}, c M n_{1}$ and $-d M n_{2}$ if we chose the orientation of the normal vectors $n_{1}, n_{2}$ as indicated in Figure 6.
We choose the orientations of the normal vectors $n_{3}, \ldots, n_{m}$ such that $d_{3}, \ldots, d_{m}<0$. Let $n_{0}:=\sum_{i=3}^{m} n_{i}$. Then the gradient of $f$ along the line segments $s_{1}, \ldots, s_{4}$ is given as follows:

| along $s_{1}:$ | $\nabla f=n_{1}+n_{2}+n_{0}$ |
| :--- | :--- |
| along $s_{2}:$ | $\nabla f=n_{1}-n_{2}+n_{0}$ |
| along $s_{3}:$ | $\nabla f=-n_{1}-n_{2}+n_{0}$ |
| along $s_{4}:$ | $\nabla f=-n_{1}+n_{2}+n_{0}$ |



Figure 6. The level set (red) for $h \in(f(0), f(0)+\varepsilon), \varepsilon>0$ small.

The gradient of $f$ along $s_{1}$ is perpendicular to $s_{1}$, hence there exists $\alpha \in \mathbb{R} \backslash\{0\}$ such that

$$
-M\left(b M n_{2}+a M n_{1}\right)=\alpha\left(n_{1}+n_{2}+n_{0}\right)
$$

or equivalently

$$
\begin{equation*}
n_{1}(a-\alpha)+n_{2}(b-\alpha)=\alpha n_{0} \tag{13}
\end{equation*}
$$

In the same way, we have

$$
\begin{align*}
n_{1}(c-\beta)+n_{2}(-b+\beta) & =\beta n_{0}  \tag{14}\\
n_{1}(-c+\gamma)+n_{2}(-d+\gamma) & =\gamma n_{0}  \tag{15}\\
n_{1}(-a+\delta)+n_{2}(d-\delta) & =\delta n_{0} \tag{16}
\end{align*}
$$

The equations (13)-(16) can only hold simultaneously if all $2 \times 2$ minors of the matrix

$$
\left(\begin{array}{rrr}
a-\alpha & b-\alpha & \alpha  \tag{17}\\
c-\beta & -b+\beta & \beta \\
-c+\gamma & -d+\gamma & \gamma \\
-a+\delta & d-\delta & \delta
\end{array}\right)
$$

vanish. In particular we have

$$
\begin{aligned}
\operatorname{det}\left(\begin{array}{ll}
b-\alpha & \alpha \\
d-\delta & \delta
\end{array}\right) & =b \delta-d \alpha=0 \\
\operatorname{det}\left(\begin{array}{ll}
-b+\beta & \beta \\
-d+\gamma & \gamma
\end{array}\right) & =-b \gamma+d \beta=0 \\
\operatorname{det}\left(\begin{array}{rr}
a-\alpha & \alpha \\
c-\beta & \beta
\end{array}\right) & =a \beta-c \alpha=0 \\
\operatorname{det}\left(\begin{array}{rr}
c-\beta & \beta \\
-a+\delta & \delta
\end{array}\right)+\operatorname{det}\left(\begin{array}{rr}
-b+\beta & \beta \\
d-\delta & \delta
\end{array}\right) & =(a-d) \beta+(c-b) \delta=0 .
\end{aligned}
$$

This is a linear system for $\alpha, \beta, \gamma, \delta$, and a nontrivial solution exists only if

$$
0=\operatorname{det}\left(\begin{array}{cccc}
-d & 0 & 0 & b \\
0 & d & -b & 0 \\
-c & a & 0 & 0 \\
0 & a-d & 0 & c-b
\end{array}\right)=b(b c d+b d a-b c a-c d a) .
$$

Recall that $b, c, d, a>0$ and hence the last condition is equivalent to

$$
\frac{1}{a}+\frac{1}{c}=\frac{1}{b}+\frac{1}{d}
$$

In summary, we have obtained the following theorem:
Theorem 2. Let $\ell_{1}, \ldots, \ell_{m}, m \geq 2$, be straight lines in the Euclidean plane, not all parallel. Assume that the sum $f(x)$ of the distances of a point $x$ to the lines $\ell_{1}, \ldots, \ell_{m}$ attains its minimum in a single point $x_{0}$ in which only two of the lines $\ell_{1}, \ldots, \ell_{m}$ meet. Then, the level sets $\left\{x \in \mathbb{R}^{2}: f(x)=h\right\}$ form a family of homothetic convex quadrilaterals for all $h \in(f(0), f(0)+\varepsilon)$ provided $\varepsilon>0$ is small enough. The intersection of the diagonals divides them into segments of lengths $b$ and $d$ on one diagonal and of lengths $c$ and $a$ on other diagonal. These lengths satisfy the conditon

$$
\begin{equation*}
\frac{1}{a}+\frac{1}{c}=\frac{1}{b}+\frac{1}{d} \tag{18}
\end{equation*}
$$

Observe that the theorem is trivially valid for $m=2$ where the level sets are rectangles.
We want to interpret condition (18) geometrically. To this end, we express the points $E$ and $F$ by the vectors $n_{1}$ and $n_{2}$ :

$$
\begin{align*}
E & =\frac{1}{a d-b c} M\left(a c(b+d) n_{1}+b d(a+c) n_{2}\right)  \tag{19}\\
F & =\frac{1}{a b-c d} M\left(a c(b+d) n_{1}-b d(a+c) n_{2}\right) \tag{20}
\end{align*}
$$

Here, we assume for the moment that the quadrilateral is neither a parallelogram nor a trapezoid, i.e., both denominators $a d-b c$ and $a b-c d$ in (19) and (20) are different from zero. Using these expressions, we find for the scalar product

$$
\langle E, F\rangle=\frac{(a b c-a b d+a c d-b c d)(a b c+a b d+a c d+b c d)}{(a d-b c)(a b-c d)}
$$

This expression is equal to 0 , if and only if the vectors $E$ and $F$ are orthogonal, and if and only if (18) holds. Thus we obtain:
Corollary 3. Let $A B C D$ be a convex complete quadrilateral which is neither a parallelogram nor a trapezoid. Then, with the notation used before, the condition (18) is equivalent to the fact that $O$ lies on the Thales circle over the segment EF (see Figure 7).

The condition (18) can be interpreted geometrically in yet another way (see Figure 8): Indeed, it is easy to check that for $a>d, b>c$ and $a=\left|O^{\prime} A^{\prime}\right|, b=\left|O^{\prime} B^{\prime}\right|, c=\left|O^{\prime} C^{\prime}\right|, d=\left|O^{\prime} D^{\prime}\right|$, the line $R S$ passes through $O^{\prime}$ if and only if the condition (18) holds - apply the intersecting chords theorem for the point $O^{\prime}$ and for the point $C^{\prime}$.
Remark 4. Note that for a rectangle (18) is trivially always satisfied. For a trapezoid we have either $a b=c d$ or $a c=b d$. Thus, (18) is equivalent to $a=d$ or $a=b$, respectively. Hence, a trapezoid satisfies (18) if and only if it is symmetric. Geometrically, the Thales circle over $E F$ degenerates for a trapezoid to the normal to the parallel sides of the trapezoid going through $E$ or $F$, and hence, under the conditon (18), to the symmetry axis of the trapezoid.

### 3.2. The case of two lines

The case of two lines is simple:
Proposition 5. Each rectangle is the level set of the sum of the distances to its diagonals. Vice versa, given two intersecting lines $\ell_{1}, \ell_{2}$, the level sets of the sum of the distances to $\ell_{1}$ and $\ell_{2}$ are rectangles with $\ell_{1}, \ell_{2}$ as diagonals.

Notice that a rectangle can also be written as the level set of the sum of the distances to $m \geq 4$ lines. Indeed, we can add to the two diagonals

- any number of pairs of parallel lines with the rectangle between them,
- any number of equilateral triangles with the rectangle in its interior,
- the pair $\ell_{1}, \ell_{2}$ more than once,
or any combination of these variants.


Figure 7. Necessary and sufficient condition for $\frac{1}{a}+\frac{1}{c}=\frac{1}{b}+\frac{1}{d}$ : The Thales circle $t$ over the segment $E F$ passes through $O$.


Figure 8. Geometric interpretation of condition (18).

### 3.3. The case of three lines

If we set $k_{1}=k_{3}$ in (9) it follows that $b=0$. A kite can therefore not be the level set of the sum of the distances to three different lines. If the quadrilateral is not a kite, then the points $P$ and $Q$ exist, and the condition $k_{1}=k_{3}$ in (8) and (12) imply

$$
\begin{equation*}
|P Q|=p \cdot \frac{b+d}{b-d} \tag{21}
\end{equation*}
$$

where we assume $b>d$. Similarly, $k_{2}=k_{3}$ yields

$$
\begin{equation*}
|P Q|=q \cdot \frac{a+c}{a-c} \tag{22}
\end{equation*}
$$

From these two equations we deduce

$$
\frac{p q}{|P Q|}=|P Q| \cdot \frac{b-d}{b+d} \cdot \frac{a-c}{a+c}=k_{3}
$$

where we have used (12) for the last equality. So, we obtain:
Theorem 6. A necessary and sufficient condition for a convex quadrilateral $A B C D$ to be the level set of the sum of the distances to three lines is

$$
\begin{equation*}
\frac{|O P||O Q|}{|P Q|}=\frac{2|O A||O C|}{|A C|}=\frac{2|O B||O D|}{|B D|}, \tag{23}
\end{equation*}
$$

where $O$ is the intersection of the diagonals $A C$ and $B D$, and where $P$ and $Q$ are the intersections of $A C$ and $B D$ with the outer diagonal.

If $A B C D$ is a quadrilateral which satisfies the condition of Theorem 6 , then the three triangle inequalities must hold in the triangle $O P Q$. If we denote $r=|P Q|$, then this means that

$$
\left(p^{2}+q^{2}+r^{2}\right)^{2}-2\left(p^{4}+q^{4}+r^{4}\right)>0
$$

(see, e.g., [5]). Using (21) and (22) this can be expressed by the inequality

$$
\begin{equation*}
(3 a b+b c+a d-c d)(a b+3 b c-a d+c d)(a b-b c+3 a d+c d)(-a b+b c+a d+3 c d)<0 . \tag{24}
\end{equation*}
$$

So, we obtain:
Corollary 7. A quadrilateral which is the level set of the sum of the distances to three lines exists if and only if the diagonal segments $a, b, c, d$ satisfy (18) and (24).

We give two constructions of quadrilaterals which are the level set of the sum of the distances to three lines.

Construction 1. Start with four segments of lengths $a, b, d, c$ which satisfy (18) such that $A^{\prime}, O^{\prime}, C^{\prime}$ are collinear with $a=\left|O^{\prime} A^{\prime}\right|>c=\left|O^{\prime} C^{\prime}\right|$, and $B^{\prime}, O^{\prime}, D^{\prime}$ are collinear with $b=\left|O^{\prime} B^{\prime}\right|>d=\left|O^{\prime} D^{\prime}\right|$ (see Figure 8). Construct the harmonic conjugate $P^{\prime}$ of $O^{\prime}$ with respect to $A^{\prime} C^{\prime}$, and the harmonic conjugate $Q^{\prime}$ of $O^{\prime}$ with respect to $B^{\prime} D^{\prime}$. Construct a segment of length $r=\left|O^{\prime} P^{\prime}\right| \frac{b+d}{b-d}$. Condition (24) is satisfied if and only if $\left|O^{\prime} P^{\prime}\right|,\left|O^{\prime} Q^{\prime}\right|$ and $r$ are the sides of a triangle $O P Q$. Then the quadrilateral $A B C D$ is easily constructed as can be seen in Figure 5 .

Construction 2. We start with three points $A O C$ with $a=|O A|>c=|O C|$ on the diagonal $\ell_{1}$ of the quadrilateral $A B C D$, and its second diagonal $\ell_{2}$ meeting $\ell_{1}$ in $O$. We need to find the points $B$ and $D$ on $\ell_{2}$. To do so, construct the harmonic conjugate $P$ of $A O C$. Observe that we have

$$
\frac{|O Q|}{|P Q|} \stackrel{\text { Thm. } 6}{=} \frac{2 a c}{(a+c)|O P|} \stackrel{(10)}{=} \frac{a-c}{a+c}=\frac{c}{\frac{2 a c}{a-c}-c} \stackrel{(10)}{=} \frac{|O C|}{|P C|} \text {. }
$$

Hence $Q$ is an intersection of $\ell_{2}$ and the Apollonian circle $K$ for this ratio which is the Thales circle over $A C$ as indicated in Figure 9.
It remains to find $B, D$ on $\ell_{2}$ such that $B, D, O, Q$ are harmonic points and such that (18) is satisfied. The construction is given in Figure 10: $K_{1}$ is the circle with diameter $O Q$, and $K_{2}$ the circle with diameter $O H$, where $|O H|=\frac{2 a c}{a+c}$, and where $O$ is between $H$ and $Q$. Then, $B$ is the intersection of the common tangents of $K_{1}$ and $K_{2}$. If $X, Y$ denote the contact points of these tangents on $K_{1}$, then $D$ is the intersection of $X Y$ and $O Q$. Let $Z$ and $W$ denote the contact points of $K_{2}$ with the tangents, and $D^{\prime}$ be the intersection of $Z W$ with $O Q$. Then $B, D, O, Q$ and $B, D^{\prime}, H, O$ are harmonic points by construction. The harmonic mean of $\left|O D^{\prime}\right|$ and $|O B|$ is $|O H|$. Since the segments on the tangents $\left|O^{\prime} O\right|=\left|O^{\prime} X\right|=\left|O^{\prime} Z\right|$ have equal lengths, it follows that $\left|O D^{\prime}\right|=|O D|$. Hence, the harmonic mean $|O D|$ and $|O B|$ is $|O H|$, and therefore (18) is satisfied, and the construction is completed.

We have learned from Construction 2 that $Q$ on $\ell_{2}$ lies on the Thales circle over $A C$. By symmetry, the point $P$ on $\ell_{1}$ is a point of the Thales circle over $B D$. We can therefore reformulate Theorem 6 geometrically as follows:


Figure 9. Construction of the point $Q$ (two solutions).


Figure 10. Construction of the points $B$ and $D$.

Theorem 8. Let $A B C D E F$ be a convex complete quadrangle with the notation used before. A necessary and sufficient condition for the quadrilateral $A B C D$ to be the level set of the sum of the distances to three lines is that the Thales circle over EF passes through $O$ and that one of the following (and consequently both) conditions hold:
(i) The Thales circle over AC on $\ell_{1}$ passes through $Q$.
(ii) The Thales circle over $B D$ on $\ell_{2}$ passes through $P$.

If $A B C D$ is a trapezoid, $E$ or $F$ lie on the ideal line. In this case, the Thales circle over $E F$ in Theorem 8 has to be interpreted as in Remark 4.

Recall that condition (18) is equivalent to the fact that the Thales circle over EF passes through $O$. We also note that according to the Bodenmiller-Steiner Theorem, the three Thales circles over the diagonals $A C, B D$ and $E F$ of a complete quadrangle meet in two points, and hence, their centers are collinear (see [3], [4], and Figure 11). The following calculation shows that the conditions (i) and (ii) in Theorem 8 together also imply (18): We have

$$
P=2 \cdot \frac{a c}{a-c} M n_{1}, \quad Q=2 \cdot \frac{b d}{d-b} M n_{2}
$$

Eliminating $\left\langle n_{1}, n_{2}\right\rangle$ from the equations

$$
\langle A-Q, C-Q\rangle=0, \quad\langle B-P, D-P\rangle=0
$$

yields again

$$
(a b c-a b d+a c d-b c d)(a b c+a b d+a c d+b c d)=0
$$

which is equivalent to (18). This gives a further possibility to reformulate the result:
Theorem 9. Let $A B C D E F$ a convex complete quadrangle with the notation used before. A necessary and sufficient condition for the quadrilateral $A B C D$ to be the level set of the sum of the distances to three lines is that the Thales circle over $A C$ passes through $Q$, and the Thales circle over $B D$ passes through $P$.


Figure 11. Necessary and sufficient conditions for a quadrilateral to be the level set of the sum of the distances to three lines.

### 3.4. The case of four or more lines

One can readily verify that actually all $2 \times 2$ minors of the matrix (17) vanish for

$$
\alpha=\frac{a(b+d)}{2 d}, \quad \beta=\frac{c(b+d)}{2 d}, \quad \gamma=\frac{c(b+d)}{2 b}, \quad \delta=\frac{a(b+d)}{2 b},
$$

if the condition (18) holds. For this choice the equations (13)-(16) coincide and yield

$$
n_{0}=n_{1} \frac{d-b}{d+b}+n_{2} \frac{c-a}{c+a}
$$

Clearly, we have $\left\|n_{0}\right\|<1$. Therefore, it is possible to choose unit vectors $n_{3}, \ldots, n_{m}$ (in particular $m=4$ ) such that

$$
n_{0}=n_{3}+\ldots+n_{m}
$$

Then we can take lines $\ell_{3}, \ldots, \ell_{m}$ with corresponding unit normale vectors $n_{3}, \ldots, n_{m}$ such that the quadrilateral lies in the half planes into which these vectors point and we obtain the following result:
Theorem 10. Every convex quadrilateral which satisfies condition (18) is the level set of the sum of the distances to 4 (or any number greater than 4) lines.

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